

Lecture 9

Expectation, Variance, Covariance, Correlation

Tay-Sachs case $\Sigma = \#$ of T-S babies out of 5, parents carriers

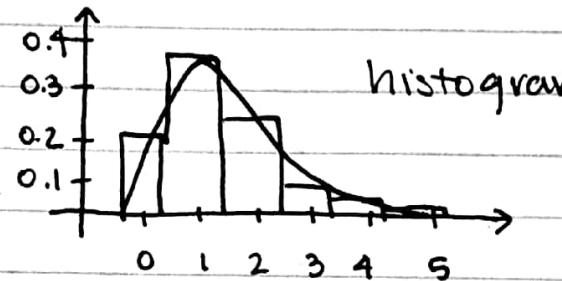
$\Sigma \sim \text{Binomial}(n, p)$ $n=5$, $p=\frac{1}{4}$

Σ	$P(\Sigma=Y)$
0	$\binom{5}{0} \left(\frac{1}{4}\right)^0 \left(\frac{3}{4}\right)^5 = 0.2373$
1	$\binom{5}{1} \left(\frac{1}{4}\right)^1 \left(\frac{3}{4}\right)^4 = 0.3955$
2	$\dots = 0.2637$
3	$= 0.0879$
4	$= 0.0146$
5	$\dots = 0.0010$

$P(\Sigma=Y) = \begin{cases} \binom{n}{y} p^y (1-p)^{n-y} & y=0,1,\dots,n \\ 0 & \text{else} \end{cases}$

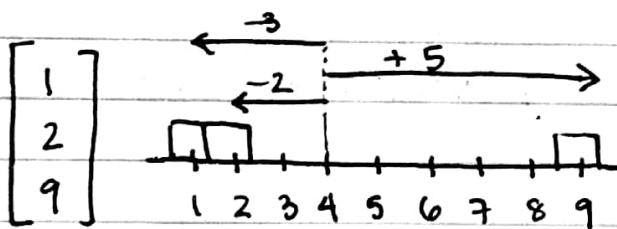
(How many T-S babies should these parents expect to have?
(center of dist. of Σ)

The most likely outcome is 1 T-S baby (the mode of the dist. of Σ).



histogram of Σ

median: 50% of probability mean ↑
above and below this point



"center of mass": balance point
mean = 4, distance to each point balances, $\sum F_i = 0$

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \dots \\ Y_n \end{bmatrix} \rightarrow \begin{bmatrix} Y_1 - c \\ Y_2 - c \\ \dots \\ Y_n - c \end{bmatrix} \sum_{i=1}^n (Y_i - c) = 0 = \left(\sum_{i=1}^n Y_i \right) - nc = 0$$

want the sum to = 0 $c = \text{center}$

deviations $C = \frac{1}{n} \sum_{i=1}^n Y_i \cong \bar{Y}$ sample mean of the dist. of Σ (sample)

Here, each value of Σ occurred only once

If some values are more probable than others, we should be able to generalize - weighted mean

A R.V. is bounded if all of its possible values are finite

lecture 9 (cont.)

Let Σ be a bounded discrete R.V. with a PMF $f_{\Sigma}(y) = P(\Sigma=y)$. The mean or expected value or expectation of Σ :

$$E(\Sigma) \triangleq \sum_{\text{all } y} y P(\Sigma=y) = \sum_{\text{all } y} y f_{\Sigma}(y)$$

$$E(\Sigma) = (0)(0.2373) + (1)(0.3955) + \dots + (5)(0.0010) = 1.2500$$

$$= \sum_{y=0}^n y \binom{n}{y} p^y (1-p)^{n-y} = \sum_{y=1}^n y \binom{n}{y} p^y (1-p)^{n-y} \quad \text{since } 0 \text{ doesn't matter}$$



$$\Sigma \sim \text{Binomial}(n, p) \text{ for } n > 1, E(\Sigma) = np \quad n \geq 1, 0 < p < 1$$

When $n=1$, Binomial(1, p) = Bernoulli(p)

$$\hookrightarrow E(\Sigma) = 0 \cdot P(\Sigma=0) + 1 \cdot P(\Sigma=1)$$

$$= 0 \cdot (1-p) + 1 \cdot p = np \text{ where } n=1 = p$$

If discrete Σ is unbounded the expectation of Σ may not exist, either because:

$$\sum_{x<0} x f_{\Sigma}(x) = -\infty \quad \text{and/or} \quad \sum_{x>0} x f_{\Sigma}(x) = +\infty$$

the distribution puts too much mass near $\pm\infty$

Σ discrete R.V. with PMF $f_{\Sigma}(x)$, if both

$$\sum_{x>0} x f_{\Sigma}(x) \text{ and } \sum_{x<0} x f_{\Sigma}(x) \text{ are infinite, } E(\Sigma)$$

is undefined or does not exist. If at least one sum is finite $E(\Sigma) = \sum_{\text{all } x} x f_{\Sigma}(x)$ exists (can be infinite)

To create a discrete R.V. whose mean doesn't exist

$$\sum_{\text{all } x} f_{\Sigma}(x) = 1 \text{ (finite) but also } \sum_{\text{some } x} x f_{\Sigma}(x) = \infty$$

Lecture 9 (cont.)

AMS 131

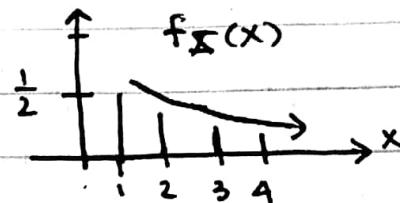
The harmonic series: $(\frac{1}{1} + \frac{1}{2} + \frac{1}{3} \dots) = \sum_{x=1}^{\infty} \frac{1}{x} = +\infty$ diverges

Cannot create a R.V. Σ with PMF $P(\Sigma=x) = \frac{c}{x}$
because the probabilities would sum to $+\infty$, but:

$$P(\Sigma=x) = \frac{c}{x^2} \text{ or } P(\Sigma=x) = \frac{c}{x(x+1)} \text{ works}$$

$$\sum_{x=1}^{\infty} \frac{1}{x^2} = \frac{\pi^2}{6} \text{ and } \sum_{x=1}^{\infty} \frac{1}{x(x+1)} = 1$$

$$f_{\Sigma}(x) = \begin{cases} \frac{1}{x(x+1)} & x=1, 2, \dots \\ 0 & \text{else} \end{cases}$$



$$E(\Sigma) = \sum_{x=1}^{\infty} x \cdot \frac{1}{x(x+1)} = \sum_{x=1}^{\infty} \frac{1}{x+1} = +\infty \quad E(\Sigma) \text{ exists, just infinite}$$

$$f_{\Sigma}(x) = \begin{cases} \frac{1}{2|x|(|x|+1)} & x = \pm 1, \pm 2, \dots \\ 0 & \text{else} \end{cases}$$

$$\sum_{\text{all } x} f_{\Sigma}(x) = 1$$

$$\text{but: } \sum_{x=-1}^{\infty} x \cdot \frac{1}{2|x|(|x|+1)} = -\infty \text{ and } \sum_{x=1}^{\infty} x \cdot \frac{1}{2x(x+1)} = +\infty$$

So $E(\Sigma)$ does not exist

Expectation for continuous R.V.s

Σ bounded, continuous with PDF

$$f_{\Sigma}(x) \rightarrow E(\Sigma) \triangleq \int_{-\infty}^{\infty} x f_{\Sigma}(x) dx$$

$$\Sigma \sim \text{Exponential}(\lambda) \quad f_{\Sigma}(x) = \begin{cases} \lambda e^{-\lambda x} & \text{for } x > 0 \\ 0 & \text{else} \end{cases}$$

$$\text{so } E(\Sigma) = \int_{-\infty}^{\infty} \lambda e^{-\lambda x} dx = \frac{1}{\lambda} \quad \begin{matrix} \text{integrate} \\ \text{by parts} \end{matrix}$$

$$\text{also } f_{\Sigma}(x) = \begin{cases} \frac{1}{\eta} e^{-\frac{x}{\eta}} & x > 0 \\ 0 & \text{else} \end{cases} \quad \begin{matrix} \Sigma \sim \text{Exponential}(\eta) (\eta > 0) \\ \eta = \frac{1}{\lambda} \quad E(\Sigma) = \eta \end{matrix}$$

Lecture 9 (cont.)

If continuous R.V. \bar{X} is unbounded with PDF $f_{\bar{X}}(y)$

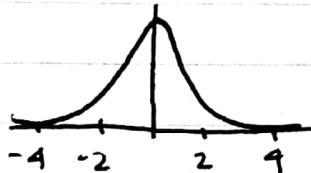
$$\int_{-\infty}^0 y f_{\bar{X}}(y) dy \text{ and } \int_0^{\infty} y f_{\bar{X}}(y) dy \quad \begin{array}{l} \text{if both are infinite,} \\ E(\bar{X}) \text{ is undefined/ DNE} \end{array}$$

If at least one integral is finite:

$$E(\bar{X}) = \int_{\mathbb{R}} y f_{\bar{X}}(y) dy \quad \text{exists, but may be infinite}$$

Cauchy distribution : $f_{\bar{X}}(y) = \frac{1}{\pi(1+y^2)}$ $-\infty < y < \infty$

$$\int_{-\infty}^{\infty} \frac{1}{\pi(1+y^2)} dy = 1$$



similar to normal, but longer tails

$$\int_{-\infty}^0 \frac{y}{\pi(1+y^2)} dy = -\infty \quad \int_0^{\infty} \frac{y}{\pi(1+y^2)} dy = +\infty \quad \begin{array}{l} \text{so } E(\bar{X}) \\ \text{DNE} \end{array}$$

the tails go to 0 extremely slow, for large y

$$\frac{y}{1+y^2} \rightarrow \frac{1}{y} \quad \text{and} \quad \int_c^{\infty} \frac{1}{y} dy = +\infty \quad \begin{array}{l} \text{continuous harmonic} \\ \text{series} \end{array}$$

Expectation of a function of a R.V.

X continuous R.V. PDF $f_X(x)$ $\bar{X} \stackrel{D}{=} h(X)$

$E[h(X)] = h[E(X)]$ would be nice, not generally true

1. work out PDF $f_{\bar{X}}(y)$, then

$$E(\bar{X}) = \int_{\mathbb{R}} y f_{\bar{X}}(y) dy \rightarrow \begin{array}{l} \text{if this exists} \\ \text{faster} \end{array}$$

2. $E(\bar{X}) = \int_{\mathbb{R}} h(x) f_X(x) dx$

Law of the
Unconscious
Statistician
(LOTUS)

discrete : $E[h(X)] = \sum_{\text{all } x} h(x) f_X(x)$

Lecture 9 (cont.)

AMS 131

$\Delta \sim \text{Exponential}(\lambda) \quad \lambda > 0 \quad E(X) = \frac{1}{\lambda} \quad I = X^2$

$$E(I) = \int_0^\infty x^2 \lambda e^{-\lambda x} = \frac{2}{\lambda^2} \quad \text{integrate by parts, twice}$$

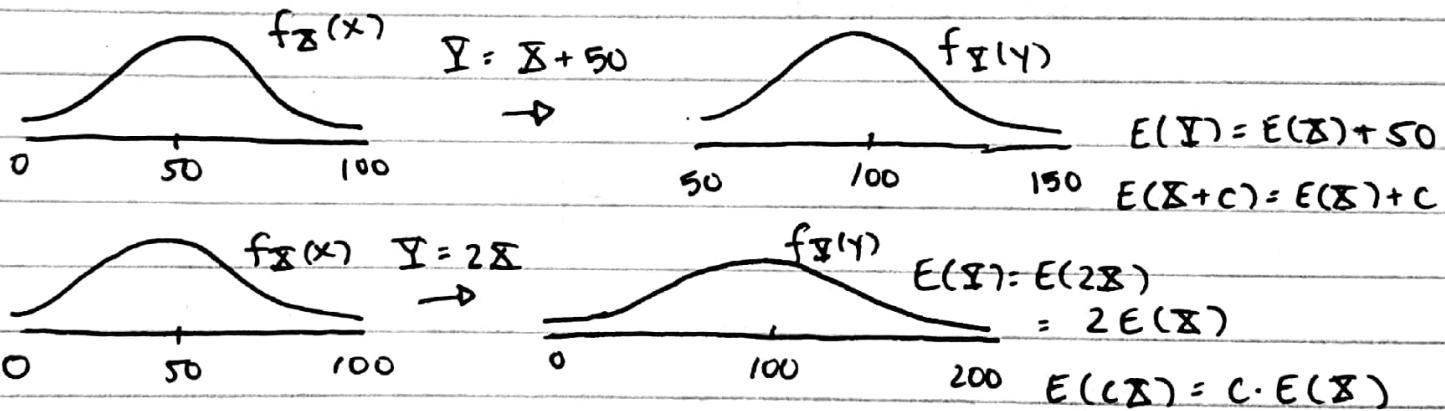
$$E(X^2) \neq [E(X)]^2$$

$$\frac{2}{\lambda^2} \neq \frac{1}{\lambda^2}$$

The only functions $I = h(X)$ for which $E[h(X)] = h[E(X)]$ are linear: $h(x) = a + bx$.

Properties 1. If $I = aX + b$, then assuming of $E(I)$ $E(I) = aE(X) + b$ $E(X)$ exists.

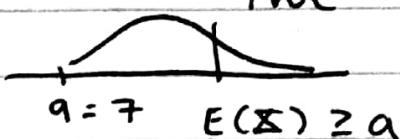
2. If you find a constant 'a' with $P(X \geq a) = 1$ then $E(X) \geq a$. If 'b' exists with $P(X \leq b) = 1$ then $E(X) \leq b$



$$E(aX + b) = aE(X) + b$$

$$\text{if } I = aX + b = h(X) \rightarrow E[h(X)] = h[E(X)]$$

$$E(X) = 3 \text{ not } \text{true}$$



$$E(X_1 + X_2) = E(X_1) + E(X_2)$$

$$E(X_1 + \dots + X_n) = E(X_1) + \dots + E(X_n)$$

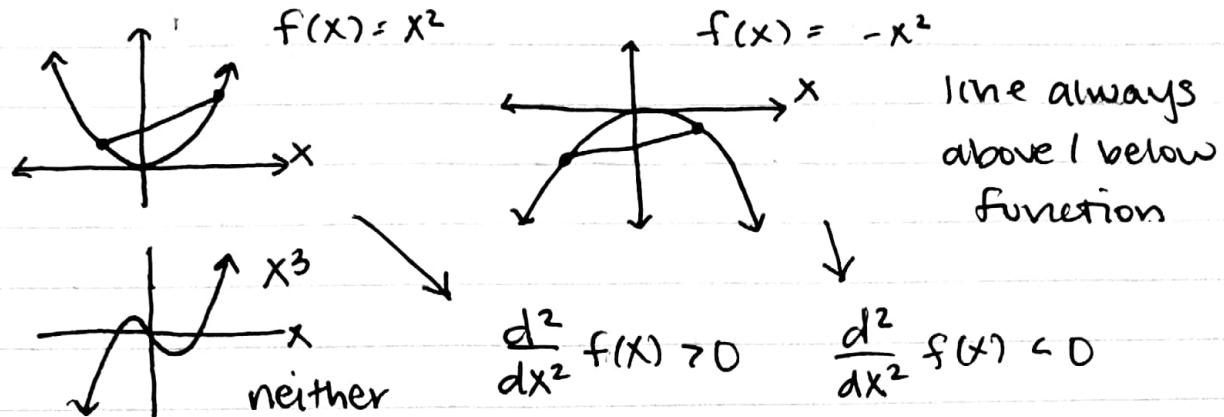
3. If X_1, \dots, X_n , each with finite $E(X_i)$, then

$$E\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n E(X_i)$$

constants

$$4. E\left[\sum_{i=1}^n (a_i X_i + b)\right] = \left(\sum_{i=1}^n a_i E(X_i)\right) + nb \quad \text{for all } a_1, \dots, a_n \text{ and } b$$

Lecture 9 (cont.)



A function $g: \mathbb{R}^n \rightarrow \mathbb{R}$, meaning $g(\underline{x}) = z$, is convex
- not imaginary value $z \rightarrow$ real #s (x_1, \dots, x_n)

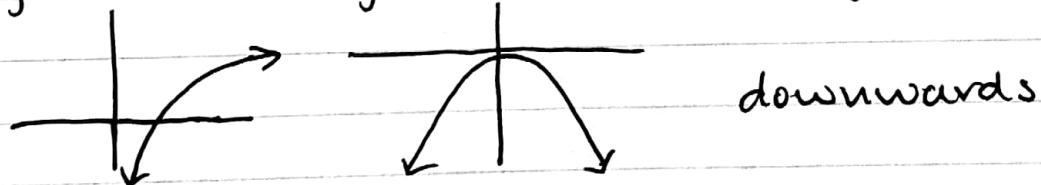
if for every $0 < \alpha < 1$ and every \underline{x} and \underline{y} ,

$$g[\alpha \underline{x} + (1-\alpha) \underline{y}] \leq \alpha g(\underline{x}) + (1-\alpha) g(\underline{y})$$

weighted averages



g is convex $g[\alpha \underline{x} + (1-\alpha) \underline{y}] \geq \alpha g(\underline{x}) + (1-\alpha) g(\underline{y})$



random vector: $\underline{\xi} = (\xi_1, \dots, \xi_n)$ $E(\underline{\xi}) \triangleq [E(\xi_1), \dots, E(\xi_n)]$

$\underline{\xi}$ random vector, finite

g convex: $E(\underline{\xi}) \rightarrow E[g(\underline{\xi})] \geq g[E(\underline{\xi})]$ Jensen's
 g concave: $E[g(\underline{\xi})] \leq g[E(\underline{\xi})]$ inequality

ex: $\xi_1, \dots, \xi_n \stackrel{\text{IID}}{\sim} \text{Bernoulli}(p)$

$$E(\xi_i) = 0 \cdot (1-p) + 1 \cdot p = p$$

$P(\xi=0)$ $P(\xi=1)$ $'p', 'n' \text{ times}$

$$E\left(\sum_{i=1}^n \xi_i\right) = \sum_{i=1}^n E(\xi_i) = n \cdot p = \begin{matrix} \leftarrow \\ \text{Binomial}(n, p) \end{matrix}$$

mean of
Binomial(n, p)

Expectation of a product when \mathbf{X}_i are independent

$$\mathbf{X}_1, \dots, \mathbf{X}_n \text{ } n \text{ R.V.} \rightarrow E\left(\prod_{i=1}^n \mathbf{X}_i\right) = \prod_{i=1}^n E(\mathbf{X}_i)$$

with finite $E(\mathbf{X}_i)$

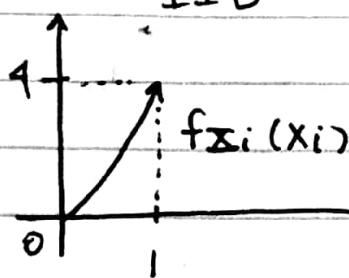
contrasted with: $E\left(\sum_{i=1}^n \mathbf{X}_i\right) = \sum_{i=1}^n E(\mathbf{X}_i)$ whether independent or not.

\mathbf{X}_1 = proportion of bad stuff removed in first filter

\mathbf{X}_2 = proportion removed in second filter, after first filter

$\mathbf{X}_1, \mathbf{X}_2$ independent, $f_{\mathbf{X}_i}(x_i) = \begin{cases} 4x^3 & 0 < x < 1 \\ 0 & \text{else} \end{cases}$

IID



$\mathbf{I} =$ proportion of bad stuff after 2 filters

$$= (1 - \mathbf{X}_1)(1 - \mathbf{X}_2)$$

↓
independence (product)

$$E(\mathbf{I}) = E[(1 - \mathbf{X}_1)(1 - \mathbf{X}_2)] = E[1 - \mathbf{X}_1] \cdot E[1 - \mathbf{X}_2]$$

$$\mathbf{X}_1, \mathbf{X}_2 \leftrightarrow (1 - \mathbf{X}_1), (1 - \mathbf{X}_2)$$

independent independent identical

$$E(1 - \mathbf{X}_1) = E(1 - \mathbf{X}_2) \stackrel{\text{def}}{=} \mu, \text{ then } E(\mathbf{I}) = \mu^2 \text{ distribution}$$

$$\mu = E(1 - \mathbf{X}_1) = \int_0^1 (1 - x_i) 4x^3 dx_i = 0.2$$

80% of bad stuff expected to be removed in 1st filtering, $E(\mathbf{I}) = \mu^2 = 0.04$, so expect only 4% of bad stuff to remain after second filtering.

a) Suppose \mathbf{X} is a discrete R.V. with possible values

$$0, 1, 2, \dots \quad E(\mathbf{X}) = \sum_{x=0}^{\infty} P(\mathbf{X} \geq x)$$

then

b) If \mathbf{X} is a continuous R.V. with possible values

$$(0, \infty) \quad E(\mathbf{X}) = \int_0^{\infty} [1 - F_X(x)] dx$$

then

CDF

a.) Throw a dart until get a bullseye (success)

Σ = # of throws until first success

FFS F = failure Success probability is constant,

$\Sigma = 3$ S = success throws are independent

$E(\Sigma)$ should be inverse to p , higher probability of hitting means you should hit it sooner.

geometric distribution at least one throw required

$$P(\Sigma \geq 1) = 1, \text{ for } n > 1$$

(at least n) = (none of the first $(n-1)$ tosses required) = (none of the first $(n-1)$ throws succeeded)

$$\text{so } P(\Sigma \geq n) = (1-p)^{n-1}$$

$$E(\Sigma) = \sum_{n=1}^{\infty} (1-p)^{n-1} = 1 + (1-p) + (1-p)^2 + \dots \quad \begin{matrix} \text{geometric} \\ \text{series} \end{matrix}$$

$$= \frac{1}{1-(1-p)} = \frac{1}{p} \quad \begin{matrix} p=0.01, \text{ succeed on 100th throw} \\ \text{inverse relationship} \checkmark \end{matrix}$$

$$\begin{bmatrix} 1 \\ 2 \\ 9 \end{bmatrix} \xrightarrow[\text{(mean)}]{} \begin{bmatrix} -3 \\ -2 \\ +5 \end{bmatrix} \xrightarrow[\text{abs.}]{} \begin{bmatrix} +3 \\ +2 \\ +5 \end{bmatrix} \quad \begin{matrix} \text{mean} = 3.33 \\ \text{MAD, mean absolute} \end{matrix}$$

$$\begin{bmatrix} y_1 \\ \dots \\ y_n \end{bmatrix} \xrightarrow{-\bar{y}} \begin{bmatrix} y_1 - \bar{y} \\ \dots \\ y_n - \bar{y} \end{bmatrix} \xrightarrow{\frac{1}{n} \sum_{i=1}^n |(y_i - \bar{y})|} \quad \begin{matrix} \text{deviations from mean} \\ \text{mean} = 0 \end{matrix}$$

$$x^2 \rightarrow \begin{bmatrix} (-3)^2 \\ (-2)^2 \\ (+5)^2 \end{bmatrix} = \begin{bmatrix} 9 \\ 4 \\ 25 \end{bmatrix} \quad \begin{matrix} \text{mean} = 12.7. \end{matrix}$$

$$\sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - \bar{y})^2} = \begin{matrix} \text{standard deviation} \\ = 3.56 \end{matrix}$$

$$\frac{1}{n} \sum_{i=1}^n (y_i - \bar{y})^2 = \text{variance [data}^2] \quad \begin{matrix} \text{same scale} \\ \text{as data} \end{matrix}$$

$$\begin{bmatrix} 1 \\ 2 \\ \vdots \\ 50 \\ \vdots \\ 100 \end{bmatrix} \xrightarrow{\text{sum}} = 101 \times 50 = 5050 \quad \text{sum (1, 100)}$$

Lecture 9 (cont.)

AMS 131

Σ discrete R.V., Uniform $\{1, 2, 9\}$ $E(\Sigma) = 4 = \mu$ (mean)
 $(\Sigma - \mu) \sim$ Uniform $\{-3, -2, +5\}$ deviation from μ
 $E(\Sigma - \mu) = 0$, so: Laplace 1785 not

$E|\Sigma - \mu| \triangleq$ mean/average absolute deviation (AAD/MAD) used
 $E(\Sigma - \mu)^2 \triangleq$ variance of R.V. Σ Gauss 1800 much

Σ . R.V. with finite mean $E(\Sigma) = \mu$

Variance of $\Sigma = V(\Sigma) \triangleq E[(\Sigma - \mu)^2]$

if $E(\Sigma) = \pm \infty$ or DNE, then $V(\Sigma)$ DNE

If Σ is in \$, $V(\Sigma) = \2 wrong units K. Pearson
 Standard deviation of $\Sigma \triangleq \sqrt{V(\Sigma)} \triangleq SD(\Sigma)$ 1890

$$\begin{aligned} V(\Sigma) &= E[(\Sigma - \mu)^2] = E[\Sigma^2 - 2\mu\Sigma + \mu^2] \\ &= E(\Sigma^2) - 2\mu E(\Sigma) + \mu^2 \\ &= E(\Sigma^2) - \mu^2 = E(\Sigma^2) - [E(\Sigma)]^2 \end{aligned}$$

$V(\Sigma) = (\text{expectation of } \Sigma^2) - (\text{square of expectation of } \Sigma)$

[1] $\Sigma \sim \text{Uniform}\{1, 2, 9\}$

$$[2] \quad \mu = 4 \quad E(\Sigma - \mu)^2 = \frac{1}{3}(1-4)^2 + \frac{1}{3}(2-4)^2 + \frac{1}{3}(9-4)^2 = 12.7$$

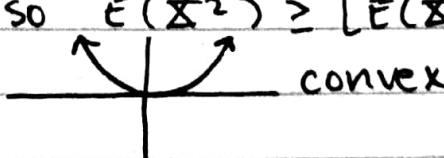
$SD(\Sigma) = \sqrt{12.7} = 3.6$ describes length of arrows

$V(\Sigma) = E(\Sigma - \mu)^2 \geq 0$, equality iff $\Sigma = \mu$, p=1

$\xrightarrow{-a} \xrightarrow{+b} a < \infty \quad V(\Sigma) < \infty$ with bounded. Σ ,
 $b < \infty$ finite

$$V(\Sigma) = E(\Sigma^2) - [E(\Sigma)]^2 \geq 0 \quad \text{so} \quad E(\Sigma^2) \geq [E(\Sigma)]^2$$

$g(x) = x^2$



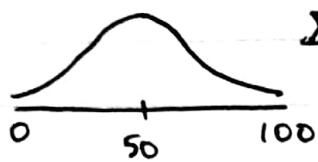
when convex $E[g(\Sigma)] \geq g[E(\Sigma)]$

$$V(\Sigma) = 0 \iff P(\Sigma = c) = 1 \quad \text{for some constant } c$$

$\underline{\quad c \quad}$: trivial R.V.

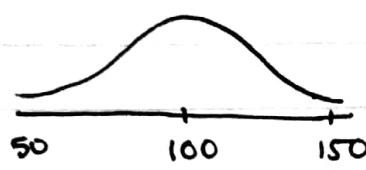
AMS 131 Lecture 9 (cont.)

$$\text{mean} = E(\bar{x}) = M_{\bar{x}}, V(\bar{x}) \triangleq \sigma_{\bar{x}}^2, SD(\bar{x}) \triangleq \sigma_{\bar{x}}$$



$$SD(\bar{x})$$

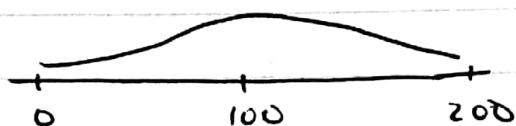
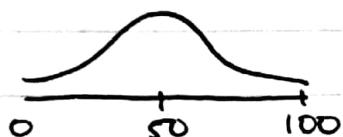
shifting does not change scale / spread



$$X + 50 = \bar{x} \quad SD(\bar{x}) = \sigma_{\bar{x}} = \sigma_x$$

$$V(\bar{x} + c) = V(\bar{x}) \quad] \text{ does not change}$$

$$SD(\bar{x} + c) = SD(\bar{x})$$



$$\bar{x} = 2\bar{x}$$

$$2SD(\bar{x}) = SD(\bar{x})$$

$$V(c\bar{x}) = c^2 V(\bar{x})$$

$$SD(c\bar{x}) = |c| SD(\bar{x})$$

$$V(a\bar{x} + b) = V(a\bar{x}) = a^2 V(\bar{x}) = a^2 SD(\bar{x})^2$$

$$SD(a\bar{x} + b) = |a| SD(\bar{x})$$

$$a=1, V(\bar{x}+c) = V(\bar{x}) \quad SD(\bar{x}+c) = SD(\bar{x})$$

$$b=0, V(a\bar{x}) = a^2 V(\bar{x}) \quad SD(a\bar{x}) = |a| SD(\bar{x})$$

if $\bar{x}_1, \dots, \bar{x}_n$ are

independent R.V. $V\left(\sum_{i=1}^n \bar{x}_i\right) = \sum_{i=1}^n V(\bar{x}_i)$

with finite means

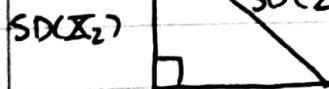
$$V(\bar{x}_1 + \bar{x}_2) = V(\bar{x}_1) + V(\bar{x}_2)$$

$$SD(\bar{x}_1 + \bar{x}_2) \neq SD(\bar{x}_1) + SD(\bar{x}_2)$$

$$SD(\bar{x}_1 + \bar{x}_2) = \sqrt{V(\bar{x}_1 + \bar{x}_2)}$$

$$\text{indep.} \quad = \sqrt{V(\bar{x}_1) + V(\bar{x}_2)}$$

$$SD(\bar{x}_1 + \bar{x}_2) = \sqrt{[SD(\bar{x}_1)]^2 + [SD(\bar{x}_2)]^2}$$



we use variance (even though

$$SD(\bar{x}_1)$$

the units are wrong) because of the additive property, SD is not